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Disentangling the free fall arch paradox in silo discharge

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Several theoretical predictions of the mass flow rate of granular media discharged from a silo are based on the spontaneous development of a *free fall arch* region whose existence is still controversial. In this work, we study experimentally and numerically the particle flow through an orifice placed at the bottom of 2D and 3D silos. The implementation of a coarse grained technique allows a thorough description of all the kinetic and micro-mechanical properties of the particle flow in the outlet proximities. Despite the *free fall arch* does not exist as traditionally understood –a region above which particles have negligible velocity and below which particles fall solely under gravity action– we discover that the kinetic pressure displays a well defined transition in a position that scales with the outlet size. This universal scaling explains why the free fall arch picture has served as an approximation to describe the flow rate in the discharge of silos.

The hourglass is a paradigmatic example of the complex behavior emerging in granular flows. In these devices, the mass flow rate is mainly controlled by the orifice size, and details like particle shape and dissipation have no great significance [1, 2]. In fact, the velocity of the grains when passing through the outlet scales only with \sqrt{gD} , where g is the gravity acceleration and D the outlet aperture [3]. This correlation has been historically associated with the existence of a singular region above the outlet, that was called *dynamic vault* by Hagen in 1852 [4]. Brown & Richards revisited Hagen’s idea and introduced the concept of *free fall arch* as a well defined spherical surface where the energy dissipation decreases to a minimum [5]; above this region grains are mainly subjected to the contacting stress and below, the material is loose and moves only under the gravity action, *i.e.* the stress in the flow direction vanishes just at this hypothetical surface [6]. The same concept was used by other authors [7, 8] to develop an alternative approach, commonly known as the *Hour-Glass Theory*, which qualitatively predicts the mass flow rate in the discharge of a silo (see [6] for a review).

Despite the popularity that the *free fall arch* idea has achieved in relation with Beverloo correlation [1], it implies the strong formal inconsistency of assuming a spatial stress discontinuity, which is difficult to justify. In addition, recent experimental efforts aimed on proving the existence of such a transition, have provided non-conclusive outcomes [9, 10]. For instance, Vivanco *et al.* conducted experiments on the flow of photoelastic disks in a two dimensional silo [9]. Examining the intensity of the force chains that appear during the discharge, they detected a well defined boundary below which force chains were very weak. Nevertheless, this region was only identified for small orifices where the flow is intermittent and arching at the orifice is prone [11–13]. Van Zuilichem *et al.* measured the density patterns in a cylindrical silo using gamma-adsorption techniques [10], finding a dilatation of the bulk close to the orifice, but a clear transition was not appreciated.

In this work, we present an extensive experimental and numerical study of the micro-mechanical properties displayed by granular media flowing through an orifice placed at the

bottom of 2D and 3D silos. Using a mathematically consistent coarse-grain averaging technique (introduced by I. Goldhirsch [14]) we describe the velocity, density and stress fields of the bulk close to the aperture. Hence, distinguishing between the kinetic and contact components of the stress tensor, we accurately identify a singular region where the granular flow changes its nature and scales with the size of the orifice. Furthermore, the mean acceleration shows the same scaling, which is totally compatible with the velocity profiles obtained at the silo outlet [3, 15]. As a result, the mass flow rate correlations previously introduced [1–3] can be consistently derived.

The experimental setup consists of a quasi-bidimensional silo built with two glass sheets (height 800 mm and width 200 mm) separated by a steel frame which also conforms the lateral walls. The gap between the glass sheets is slightly larger than the particles diameter ($d = 2r_p = 1.0$ mm) so the beads can only arrange themselves in a single layer. The particles flow out through a horizontal slit of a tunable aperture $D = 2R$ located at the flat bottom of the silo. The discharge process is recorded by means of a high speed camera. The videos were analyzed using image processing techniques allowing a precise determination of the instantaneous position \vec{r} and velocity \vec{v} of each particle. A more detailed description of the experimental setup and image analysis techniques can be found in [13] and [3] respectively.

In order to get access to the micro-mechanical properties of the system and extend the experimental findings in two dimensions to a more realistic 3D silo, we have resorted to numerical simulations. A hybrid CPU-GPU Discrete Element [17, 18] algorithm has been developed for a system of spheres with diameter $d = 2r_p = \frac{1}{32}$ m and density $\rho = 7520$ kg/m³. The contact interaction has been simulated using a linear-dashpot model with normal and tangential elastic constants, $k_n = 10^8$ N/m and $k_t = \frac{2}{7}k_n$, respectively. The ratio between normal and tangential damping coefficients was taken as $\frac{\gamma_n}{\gamma_t} = 3$ with $\gamma_n = 10^3$ s⁻¹. Accordingly, the equations of motion were integrated with $\Delta t = 10^{-6}$ s (more details can be found in [15, 18]). A flat bottom cylindrical container is implemented with a radius $W = 32 \times r_p$ and walls with equivalent mechanical properties than these of the particles. We generate a gran-

ular column from a granular gas of $N = 262144$ spheres that are initially located within the cylinder at random locations. Then, they settle under the effect of gravity and are allowed to leave the system through a circular outlet centered at the bottom of the column. After certain time, a steady state is reached with a column height of around $h_{max} = 112 \times d$.

The kinetic and dynamic properties of the particle flow have been examined using a consistent coarse graining methodology [14, 19]. First, we have accessed to the exact positions and velocities of the particles in the experiments and numerical simulations. Then, the coarse-grained mass density of a granular flow, $\rho(\vec{r})$, at time t is obtained as: $\rho(\vec{r}) = \sum_{i=1}^N m_i \phi(\vec{r} - \vec{r}_i(t))$ where the sum runs over all particles within the system and $\phi(\vec{r} - \vec{r}_i(t))$ is an integrable coarse-graining function [14]. In the same way, the coarse grained momentum density function $P(\vec{r}, t)$ can be defined by: $P(\vec{r}, t) = \sum_{i=1}^N m_i \vec{v}_i \phi(\vec{r} - \vec{r}_i(t))$, where \vec{v}_i represents the velocity of particle i . The macroscopic velocity field $\vec{V}(\vec{r}, t)$ is then defined as the ratio of momentum and density fields, $V(\vec{r}, t) = P(\vec{r}, t) / \rho(\vec{r}, t)$.

The macroscopic stress field $\sigma_{\alpha\beta}$ can be decomposed into a contact stress field ($\sigma_{\alpha\beta}^c$) related with particle-particle interactions, and a kinetic stress field ($\sigma_{\alpha\beta}^k$) which depends on the velocity fluctuations of a single particle respect to the macroscopic flow [14]. The contact stress reads:

$$\sigma_{\alpha\beta}^c = -\frac{1}{2} \sum_{i=1}^N \sum_{j=1}^{N_{ci}} f_{ij\alpha} r_{ij\beta} \int_0^1 \phi(\vec{r} - \vec{r}_i + s\vec{r}_{ij}) ds \quad (1)$$

where the first sum runs over all the particles and the second accounts for the N_{ci} contacting particles of i . Moreover, \vec{f}_{ij} accounts for the force exerted by particle j on particle i and $\vec{r}_{ij} \equiv \vec{r}_i - \vec{r}_j$. The kinetic stress reads:

$$\sigma_{\alpha\beta}^k = -\sum_i^N m_i \vec{v}_{i\alpha} \vec{v}_{i\beta} \phi(\vec{r} - \vec{r}_i), \quad (2)$$

where $\vec{v}_i'(\vec{r}, t) = \vec{v}_i(t) - \vec{V}(\vec{r}, t)$.

Based on these definitions, we have implemented a post-processing tool to resolve the kinetic fields in the 2D (experimental) and 3D (numerical) discharge processes. In complement, all the micro-mechanical properties of the simulated flow have been explored in detail. We use a Gaussian coarse-graining function, $\phi(\vec{\mathcal{R}}) = \frac{1}{(\sqrt{2\pi}w)^3} \exp\left(-\frac{|\vec{\mathcal{R}}|^2}{2w^2}\right)$, with $\vec{\mathcal{R}} = \vec{r} - \vec{r}_i$, and the coarse-graining scale has been always kept $w = r_p$. The fields are explored at a region close to the outlet for a range of apertures $8r_p < R < 26r_p$, so guaranteeing absence of clogging. In all cases, the temporal averaging of the variables is computed along the whole measurement time. In the 3D silo, cylindrical averaging around the vertical axis is also performed. Thus, the magnitudes are displayed as 2D azimuthal averages where r represents the radial distance to the center of the outlet.

First, we show the spatial dependence of the vertical velocity, v_z , and volume fraction fields within the 2D and 3D silos

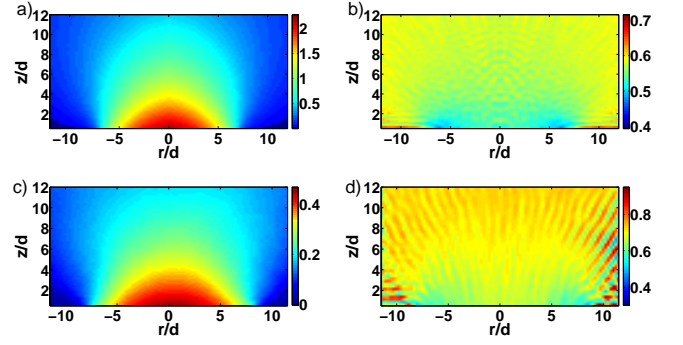


FIG. 1. (Color online) Vertical velocity (left) and solid fraction (right) fields for the 3D numerical (top) and 2D experimental (bottom) silos. In all cases $R = 16r_p$ and a Gaussian coarse-graining function $\phi(\vec{\mathcal{R}})$ with $w = r_p$ has been used. In the figures, the vertical coordinate, z , indicates the height from the bottom of the silo, and the horizontal coordinate, r , the distance to center of the silo.

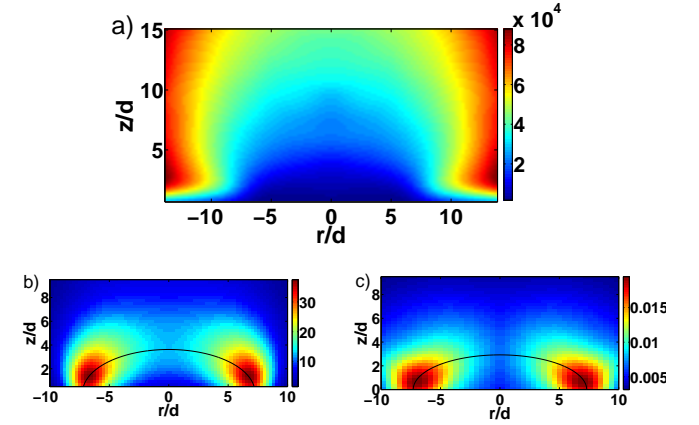


FIG. 2. (Color online) a) *Contact pressure* $tr[\sigma_{\alpha\beta}^c]$ profile obtained from simulations. At the bottom, spatial profiles of the b) numerical and c) experimental *kinetic pressure*. The line is a parabolic fitting of the local maximum position. All graphs correspond to $R = 16r_p$ and the data have been calculated with a Gaussian coarse-graining function $\phi(\vec{\mathcal{R}})$ and $w = r_p$.

(Fig 1). In both situations the coarse-graining magnitudes display monotonous behavior with height: when approaching the orifice, velocity increases and volume fraction decreases. For completeness we have checked that the kinetic profiles at $z = 0$ are coherent with previous results [3, 15].

Next, we investigate the micromechanical details of the particle flow by focusing on the changes in the mean kinetic and contact tensors. The spatial profile of the *contact pressure*, defined as the trace of $\sigma_{\alpha\beta}^c$, is illustrated in Fig 2a. As the height is reduced, the contact stress monotonically decreases due to dilatation of the bulk [10], which is compatible with the density fields shown in Fig 1. Additionally, the correlation between the traction transmission and the velocity fluctuations can be outlined examining the *kinetic stress*. Importantly, this magnitude is also accessible for the experimental case as it only depends on the fluctuations of the particle's

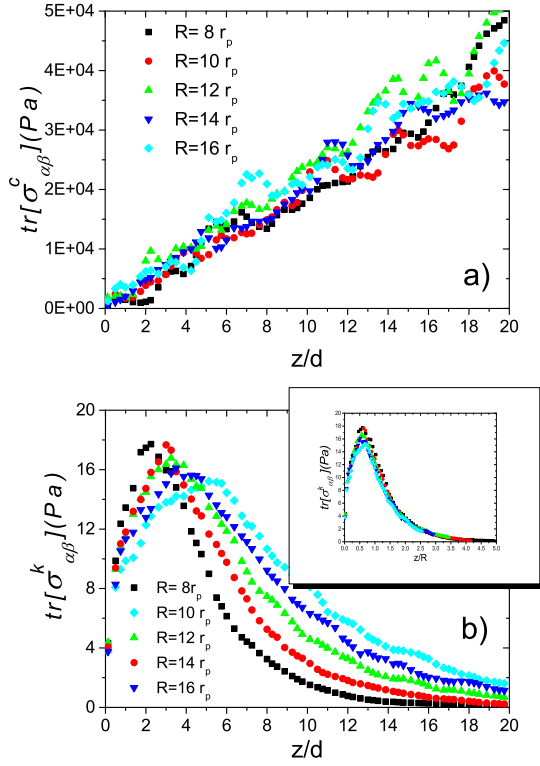


FIG. 3. (Color online) Vertical profiles of a) *contact pressure*, $tr[\sigma_{\alpha\beta}^c]$, and b) *kinetic pressure*, $tr[\sigma_{\alpha\beta}^k]$, at the center of the silo ($r = 0$), for different outlet sizes R as indicated in legend. The inset shows the data collapse when normalizing the vertical coordinate z with the size of the outlet R .

velocity respect to the macroscopic flow. As in the case of $\sigma_{\alpha\beta}^c$, we quantify the strength of the *kinetic pressure* with the trace of $\sigma_{\alpha\beta}^k$ (Eq. 2). The obtained values (Fig 2b-c) are several orders of magnitude smaller than the *contact pressure*, but the spatial pattern looks very different. Both, experimental and numerical outcomes, show non monotonous trends indicating the existence of a region where the kinetic pressure is maximum. Note that the existence of a low-pressure cavity above the outlet was already observed by implementing a plastic rheology in a 2D Navier-Stokes solver following the $\mu(I)$ -rheology [16].

For sake of simplicity, we focus on the evolution of the *contact* and *kinetic pressure* along the vertical direction z at the center of the orifice. As evidenced in Fig 2a, the *contact pressure* decays monotonically when approaching the bottom of the silo (Fig. 3a). Remarkably, the gradient of *contact pressure* is constant (typically of the same order of magnitude than the gravity body force $\rho g \phi(r, z)$) and nearly independent on the outlet size. Consequently, a region resembling a *free-fall arch* (that should scale with R) can not be inferred from these findings. Meanwhile, the kinetic pressure shows a non-monotonous behavior (Fig. 3b). Far from the outlet, particles follow a global macroscopic laminar flow where advection dominates their movements and, as consequence, the *kinetic pressure* is negligible. As the height decreases, the

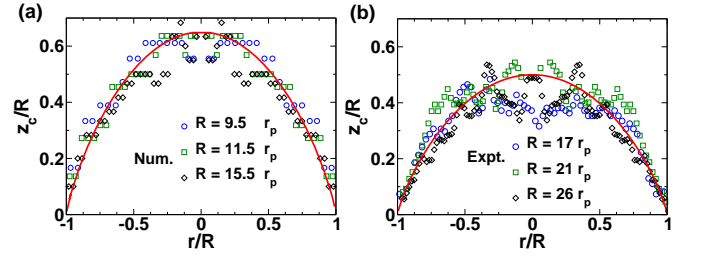


FIG. 4. (Color online) Position of the local maximum of the kinetic stress as a function of the radial distance for (a) 3D (numerical) and (b) 2D (experimental) silos. All the data have been collapsed normalizing the vertical and horizontal distances with the radius of the outlet. The red lines correspond to a parabolic fit which can be associated to the modified concept of *free fall arch*.

kinetic pressure grows exponentially till it reaches a well defined maximum which location z_c depends on R . Indeed, the *kinetic pressure* profiles can be collapsed normalizing the vertical coordinate with R (inset of Fig. 3b). Hence, although the kinetic stress is much smaller than the contact stress, the scaling of its spatial profile with R suggests its importance in the discharge process.

In order to unveil the relationship between the spatial dependence of *kinetic pressure* and the shape of velocity profiles at the outlet, Fig 4 illustrates the vertical position, z_c , for which the *kinetic pressure* is maximum, as a function of the radial distance, r . All curves obtained for different outlet sizes can be collapsed by rescaling both, z_c and r , by the outlet size, R . More importantly, the collapsed data can be fitted by a parabolic dome. Although the height of these domes seems to depend on the dimensionality, the collapse prompts us to reframe the concept of *free fall arch* as the region where the collisional part of the stress tensor starts to diminish and the dynamics becomes gradually dominated by the external field. This picture contrasts with the traditional view of a location where the velocity is negligible and grains start a free fall.

The unsuitability of this historical idea can be confirmed by examining the effective acceleration profiles $a_{eff} = dv_z/dt$. The experimental and numerical outcomes of $a_{eff}(z)$ at the center of the orifice ($r = 0$) and along the vertical direction ($h = z/R$) are shown in Fig 5. The values of $a_{eff}(z)$ were calculated by finite differencing the velocity vector of a single particle in two consecutive times (in simulations $\Delta t_s = t_d/8$, and in experiments $\Delta t_e \approx t_d/4$, where $t_d = \sqrt{2d/g}$). The data shown correspond to averages over square (2D) or cubic (3D) regions of width $\Delta = 2r_p$. Similar to the *kinetic stress*, the vertical acceleration profiles collapse into a single master curve when z is normalized by R . Remarkably, for both the 2D and 3D silos, the collapse is very robust and the curve trends are similar: as particles move down, acceleration increases, and it only equals the gravity at the very outlet. For comparison, the acceleration profiles expected from the traditional picture of *free fall arch* are illustrated by a Heaviside function (shadowed region in Fig 5). Incidentally, acceleration values slightly greater than g seem to appear close to the aperture. We

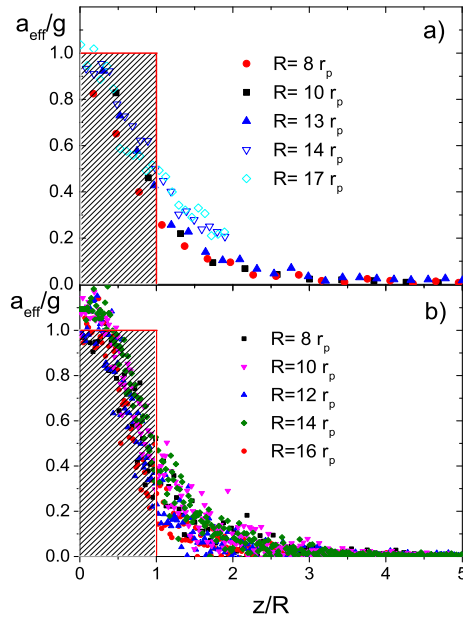


FIG. 5. (Color online) Effective acceleration normalized by the gravity as a function of the normalized vertical distance z/R in a) a 2D experimental silo, and b) a 3D numerically simulated silo. In both cases, the measurements have been performed at $r = 0$. The shadow region corresponds to the Heaviside function compatible with the historical idea of the *free fall arch*.

speculate that the origin of such an excess of acceleration is caused by particles being ejected downwards which indicates that the system compression is still significant at this location.

The observations reported in Fig. 5 seem to challenge the validity of the scaling $v_c = \sqrt{2\gamma g R}$, where $\gamma = 1.07 \pm 0.015$ was a fitting parameter, experimentally obtained from the dependency of v_c on R [3]. Far from that, the self-similarity of the acceleration profiles is the key that provides the argument to analytically calculate the scaling function v_c as follows. First, the vertical evolution of the acceleration is generally written as $\mathcal{F}(h) = \frac{a(h)}{g}$ where $\mathcal{F}(h)$ is a self-similar function of $h = z/R$. After a simple change of variables, this expression can be rewritten as: $v dv = gR \mathcal{F}(h) dh$. Then, we integrate assuming that the silo expands over the upper half plane, with the outlet centered at the origin:

$$\int_0^{v_c} v dv = \frac{v_c^2}{2} = gR \int_{-\infty}^0 \mathcal{F}(h) dh = \gamma gR \quad (3)$$

Straightforwardly $v_c = \sqrt{2\gamma g R}$, where γ accounts for the area under the curves of Fig 5. We have obtained $\gamma = 1.10$ and $\gamma = 1.09$ for the 2D experimental and 3D numerical cases, respectively. Following the original hypothesis of *free fall arch* the value of γ would be equal to one. As a consequence, founded on the self-similarity of the dynamical fields inside the silo, the scaling ansatz introduced in [3] is totally justified. Indeed, it can be stated that the scaling $v_c \propto \sqrt{gR}$ is imposed by the fact that R is the only relevant length scale in the system, and the asymptotic evolution of the acceleration towards

the gravity value g .

In summary, our findings disentangle the paradoxical ideas associated to the *free fall arch* in the discharge of a silo which has historically served to justify the flow rate dependence on the outlet size. As early suggested [4], it exists a singular region above the outlet where certain dynamical features decide the resulting velocity profile. Nevertheless, by no means this region meets the naive picture of an arch where particles loose all their kinetic energy and start to fall freely under gravity. In the same way, discontinuities in the stress field [5, 7, 8] have been neither identified. We have shown that the stress decomposition into contact and kinetic parts [14] provides a suitable theoretical framework to distinguish between the different role of force chains and velocity fluctuations. The *contact pressure* displays a constant decrease as ones approaches to the exit. This behavior is practically independent of the aperture size, indicating that the pressure inside the silo has not a one to one relationship with the velocity profile at the exit, as was already suggested in [20]. Meanwhile, the *kinetic pressure* displays a well defined maximum near the outlet that defines a transition surface. The scaling of this surface with the size of the aperture links the microscopic dynamics observed for the discharge process with the stress fields, suggesting that the only relevant length scale in the problem is R . At this point, the independence of contact pressure with R might result surprising. However, it is important to remark that all the examined fields represent a continuum description of our granular system in stationary conditions. In fact, the advective motion of a representative volume element (*RVE*) is governed by the momentum balance in terms of the gravity, the gradient of *contact pressure* and the dissipative shear stress. For symmetry reasons, at the center of the silo the shear stress diminishes and maximum values of the vertical velocity V_{max} are developed. As the gradient of *contact stress* is constant, regardless the outlet size, it is plausible to accept that V_{max} is controlled by the distance from the *RVE* to the border of the orifice, which is in agreement with the role of R as the only characteristic length of the discharge process. Finally, based on the acceleration profiles collapse with R , we explain the scaling of the exit velocity with \sqrt{gR} [3, 15] as well as the traditional mass flow rate correlations used in engineering [1, 2].

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